

In the Specification:

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Amend the paragraphs at page 13, lines 16-24 as follows

--In one configuration, the animal is milked from a rearward milking unit [[60]]. That is, the milking unit [[60]] comes from behind the animal and through the rear legs of the animal to access the teats.

In a further configuration, the milking unit [[60]] comes up through the floor of the stall directly under the udder of the animal. An actuating mechanism for the milking unit [[60]] can pass between the rear legs, from the side of the animal or from beneath the animal. --

Amend the paragraph at page 17, lines 24-27as follows

--The milking process is then performed, with the teats being accessed from between the rear legs of the animal. For example, the robotic actuating arm [[94]] 44 can locate the milking unit [[60]] relative to the teats for milking.--